# Cuyler Crandall

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### EDUCATION

### CORNELL UNIVERSITY

M.ENG, MECHANICAL ENGINEERING May 2020 | Ithaca, NY

### CORNELL UNIVERSITY

BS, MECHANICAL ENGINEERING

December 2019 | Ithaca, NY College of Engineering *Magna Cum Laude* Cumlative GPA: 3.81 / 4.0

### LINKS

LinkedIn:// cuylercrandall Portfolio:// cuylercrandall.com

# COURSEWORK

#### GRADUATE

Multivariable Control Systems Feedback Control Systems Embedded OS Autonomous Mobile Robots Architectural Robotics

#### UNDERGRADUATE

Mechanical Synthesis (*Two-Time TA*) Design for Manufacturing & Assembly Computer-Aided Manufacturing Design Failure Mode & Effect Analysis Spaceflight Mechanics

### SKILLS

### DESIGN AND ANALYSIS

Professional Use: Catia 3DX • Catia V5 • SolidWorks GD&T • MATLAB • &TEX Familiar: Inventor • NX • Fusion 360 • Python

### FABRICATION

Mass Production Injection Molding • Wireharnesses Sheet Metal Stamping **Rapid Prototyping** 3D Printing (FDM/SLA/SLS/MJF) Laser Cutting **Metalworking** CNC machining on Haas VMCs Manual mills & lathes

## PROFESSIONAL EXPERIENCE

#### **TESLA** | MECHANICAL DESIGN ENGINEER, HIGH VOLTAGE DISTRIBUTION Aug 2020 - Present | Palo Alto, CA

- Designing automotive HV connectors, devices, and wireharness assemblies
- Carrying concepts from one-off prototypes to high volume production
- Validating parts to IP67, IP69K, and various environmental conditions
- Working cross-functionally with electrical, test, manufacturing,  $\&\ service\ teams$

#### AIRBNB | MECHANICAL ENGINEERING INTERN

May 2019 – Aug 2019 | San Francisco, CA

- On the **Backyard** team, prototyped new ways that homes can be built & shared
- Designed for near-term deliverables while retaining long-term adaptability
- Built prototypes for industrial designers to refine user experience

#### HONEYBEE ROBOTICS | MECHANICAL ENGINEERING INTERN

May 2018 – Aug 2018 | Pasadena, CA

- Designed sample manipulation system parts for NASA mission Dragonfly
- Released drawings and components to NASA Goddard Space Flight Center
- Constructed cryogenic test fixtures for helium leak testing

### ON-CAMPUS EXPERIENCE

#### CORNELL UNIVERSITY AUTONOMOUS UNDERWATER VEHICLE Aug 2016 – May 2020 | Ithaca, NY

- Leader of the 12 member mechanical subteam for 2 years
- Organized meetings, design reviews, and training for new members
- Designed and manufactured experimental underwater vector thrust modules

#### ARCHITECTURAL ROBOTICS LAB | MECHANICAL DESIGNER

Jan 2020 – May 2020 | Ithaca, NY

- Worked under PhD candidate **Deanna Kocher** in Keith Green's lab
- Contributed to Growbot, a robot to teach children to care for houseplants

### MAE 2250: MECHANICAL SYNTHESIS | UNDERGRAD/GRAD TA

Jan 2019 – May 2020 | Ithaca, NY

- Trained sophomores in CAD, rapid prototyping, and on manual mills and lathes
- Facilitated design reviews & gave pre-production feedback on groups' designs

### AWARDS

2020	Best Demo	2020 ACM Interaction Design and Children Conference [1]
2017	1 <sup>st</sup> , Overall	AUVSI International Robosub Competition
2017	1 <sup>st</sup> , Tech Report	AUVSI International Robosub Competition

### PUBLICATIONS

 D. Kocher, C. Crandall, C. Yuan, and K. Green. Growbot: a robotic system to help children grow plants. 2020 ACM Interaction Design and Children Conference: Extended Abstracts (IDC '20), 2020.